	-
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detector or sensor) and (calibrating or alignment or test) EP DE IBN 2 1519 beam with (source or emitter or laser or trasmitter) with (receiver or US)	Time stamp 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21 2003/09/21	
EPODE IBM 2 1519 beam with (source or emitter or laser or trasmitter) with (receiver or US)	O; JPO; ERWENT; M_TDB JPAT; 2003/09/21 I-PGPUB;	
EPODE 1519 beam with (source or emitter or laser or trasmitter) with (receiver or US)	ERWENT;	
DE IBN 2 1519 beam with (source or emitter or laser or trasmitter) with (receiver or US	ERWENT;	
2 1519 beam with (source or emitter or laser or trasmitter) with (receiver or US	M_TDB	
	-PGPUB;	
	-PGPUB;	15:35
	ERWENT;	
	M_TDB	
	SPAT; 2003/09/21	15:34
	B-PGPUB;	13.51
	О; ЛРО;	
	ERWENT;	
	M_TDB	15.24
	SPAT; 2003/09/21	15:34
	S-PGPUB;	
	О; ЛРО;	
	ERWENT;	
	M_TDB	
	SPAT; 2003/09/21	15:34
	S-PGPUB;	
or grid or filter) and 250/\$.ccls.) and lengths with (path or beam)	Ю; ЈРО;	
DE	ERWENT;	
	M_TDB	
6 715 beam with (source or emitter or laser or trasmitter) with (receiver or US	SPAT; 2003/09/21	15:38
detector or sensor) and (calibrating or alignment or test) with (blocking US	S-PGPUB;	
	Ю; ЛРО;	
	ERWENT;	
	M_TDB	
	SPĀT; 2003/09/21	15:38
	S-PGPUB;	
or filter)	РО; ЛРО;	
DE	ERWENT;	
	M_TDB	
	SPAT; 2003/09/21	15:39
	S-PGPUB;	
	РО; ЛРО;	
	ERWENT;	
	M_TDB	
	SPAT; 2003/09/21	15:40
	S-PGPUB; 2003/09/21	. JTU
	PO; JPO;	
	ERWENT;	
	* 1	
	M_TDB 2003/00/21	15.40
	SPAT; 2003/09/21	13.42
	S-PGPUB;	
	PO; JPO;	
	ERWENT;	
	M_TDB	
	SPAT; 2003/09/21	15:43
	S-PGPUB;	
	РО; ЛРО;	
	ERWENT;	
	M_TDB	
13 2 modulator with test near alignment US	SPAT; 2003/09/21	15:43
	S-PGPUB;	
EP	РО; ЛРО;	
	ERWENT;	
	M TDB	

11	4	grid with test near alignment	USPAT;	2003/09/21 15:46
			US-PGPUB;	
			ЕРО; ЛРО;	
	1		DERWENT;	
			IBM_TDB	
14	4	5969756.URPN.	USPAT	2003/09/21 15:44
15	14	("3962722" "4330779" "4415921" "4575753" "4688079"	USPAT	2003/09/21 15:44
	1	"4751570" "4754329" "4760444" "4814858" "4893925"		
		"5032769" "5049791" "5216504" "5371537").PN.		
16	229712	calibrat\$3 or (alignment adj test)	USPAT;	2003/09/21 15:46
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM_TDB	
17	11686	(calibrat\$3 or (alignment adj test)) same filter	USPAT;	2003/09/21 15:46
			US-PGPUB;	
			ЕРО; ЈРО;	
	1		DERWENT;	
			IBM_TDB	
18	2783	(calibrat\$3 or (alignment adj test)) same filter and sensor and source	USPAT;	2003/09/21 15:46
	1		US-PGPUB;	
			EPO; JPO;	1
			DERWENT;	
			IBM_TDB	2002/00/21 17 :=
19	1444	(calibrat\$3 or (alignment adj test)) same filter and receiver and source	USPAT;	2003/09/21 15:47
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	2002/00/21 15 40
20	4197	(source or emitter or laser) and (detector or receiver or sensor) and (grid	USPAT;	2003/09/21 15:48
		or pattern or filter) with calibrat\$3	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	(22)	() () () () () () () () () ()	IBM_TDB USPAT;	2003/09/21 15:48
21	6221	(source or emitter or laser) and (detector or receiver or sensor) and (grid	US-PGPUB;	2003/09/21 13.48
		or pattern or filter) with alignment	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
22	10015	((source or emitter or laser) and (detector or receiver or sensor) and	USPAT;	2003/09/21 15:48
22	10013	(grid or pattern or filter) with calibrat\$3) or ((source or emitter or laser)	US-PGPUB;	2003/03/21 13:10
		and (detector or receiver or sensor) and (grid or pattern or filter) with	EPO; JPO;	
	1	alignment)	DERWENT;	
		ungument)	IBM_TDB	
23	1684	(((source or emitter or laser) and (detector or receiver or sensor) and	USPAT;	2003/09/21 15:49
23	1004	(grid or pattern or filter) with calibrat\$3) or ((source or emitter or laser)	US-PGPUB;	
		and (detector or receiver or sensor) and (grid or pattern or filter) with	ЕРО; ЛРО;	
		alignment)) and 250/\$.ccls.	DERWENT;	
			IBM_TDB	
24	52	((((source or emitter or laser) and (detector or receiver or sensor) and	USPAT;	2003/09/21 15:50
		(grid or pattern or filter) with calibrat\$3) or ((source or emitter or laser)	US-PGPUB;	
		and (detector or receiver or sensor) and (grid or pattern or filter) with	ЕРО; ЛРО;	
		alignment)) and 250/\$.ccls.) and path adj lengths	DERWENT,	
			IBM_TDB	
25	1	alignement with sensor with source same (filter or grid or valve or	USPĀT;	2003/09/21 15:51
		osbcuring)	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT,	
			IBM_TDB	
26	18	alignment with sensor with source same (filter)	USPAT;	2003/09/21 15:54
		- ,	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	

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27	54	test with sensor with source same (filter)	USPAT; US-PGPUB;	2003/09/21 15:54
			ЕРО; ЛРО;	
			DERWENT;	
1				
20		(C14 - N - S4 - 15 - 4 - 11 -	IBM_TDB	2002/00/21 15.55
28	0	test with sensor with source same (filter) with adjustable	USPAT;	2003/09/21 15:55
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
29	0	test with sensor with source same (filter) with controllable	USPAT;	2003/09/21 15:55
			US-PGPUB;	
•			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
30	6	test with sensor with source same (filter) with level	USPAT;	2003/09/21 15:55
30	ľ	test with believe with source same (liver) with level	US-PGPUB;	2002103721 12.22
			EPO; JPO;	
			DERWENT;	
	_	4 4 4 1 1 1 4 4 4 4 4 4 4 4 4 4 4 4 4 4	IBM_TDB	2003/09/21 15:56
31	6	test with sensor with source same (filter) and path adj lengths	USPAT;	2003/09/21 15:56
			US-PGPUB;	
			ЕРО; ЈРО;	
	1		DERWENT;	
			IBM_TDB	
32	0	alignment with sensor with source same (filter) and path adj lengths	USPAT;	2003/09/21 15:56
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
33	13	alignment with sensor with source same (filter) and lengths	USPĀT;	2003/09/21 16:00
]		US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
34	0	alignment with sensor with source same (filter) and self adj test	USPAT;	2003/09/21 16:00
34		alignment with sensor with source same (mer) and sen adjuest	US-PGPUB;	2003/03/21 10:00
			EPO; JPO;	
			DERWENT;	
1 25	_	11	IBM_TDB	2002/00/21 16:00
35	0	alignment with sensor with source same (filter) and self-test	USPAT;	2003/09/21 16:00
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM_TDB	
36	9	alignment with sensor with source same (filter) and calibrat\$3	USPAT;	2003/09/21 16:08
	1		US-PGPUB;	
	1		ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
37	1	"6359278" and alignment	USPAT;	2003/09/21 16:10
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
38	0	"6359278" and lengths	USPAT;	2003/09/21 16:10
30		0337210 and lengths	US-PGPUB;	2003/03/21 10:10
	ļ		EPO; JPO;	
			DERWENT;	
L	L		IBM_TDB	

39	0	"6359278" and distance	USPAT;	2003/09/21 16:10
39		0339278 and distance	US-PGPUB;	2003/03/21 10:10
}			EPO; JPO;	
			DERWENT;	
1			IBM_TDB	2002/00/21 16 11
40	500	alignment with source with sensor and distances	USPAT;	2003/09/21 16:11
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
41	193	alignment with source with sensor and (lengths or distances)	USPAT;	2003/09/21 16:11
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM_TDB	
42	12	alignment with source with sensor same (lengths or distances)	USPAT;	2003/09/21 16:12
-		,	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
43	7	alignment with source with sensor and plurality with (lengths or	USPAT;	2003/09/21 16:12
43	'	distances)	US-PGPUB;	2003/03/21 10:12
		distances)	ЕРО; ЛРО;	
			DERWENT;	
		1'	IBM_TDB	2003/09/21 16:12
44	0	alignment with source with sensor and plurality adj (lengths or	USPAT;	2003/09/21 10.12
		distances)	US-PGPUB;	
1			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	2002/00/01 17 12
45	0	alignment with source with sensor and plurality adj (lengths or	USPAT;	2003/09/21 16:12
		distances)	US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM_TDB	
46	0	alignment with source with sensor and number adj (lengths or distances)	USPAT;	2003/09/21 16:12
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
47	17	alignment with source with sensor and different adj (lengths or	USPAT;	2003/09/21 16:14
		distances)	US-PGPUB,	
1		, ,	EPO; JPO;	
			DERWENT;	
1	1		IBM_TDB	
48	7	alignment with source with sensor and filter and different adj (lengths or	USPĀT;	2003/09/21 16:16
'-		distances)	US-PGPUB;	
		,	ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
49	0	alignment with source with sensor and attenuator and different adj	USPAT;	2003/09/21 16:16
"		(lengths or distances)	US-PGPUB;	
		(tenguis or distances)	ЕРО; ЛРО;]
			DERWENT;	
			IBM_TDB	
50		alicement with gaves with songer and attenuator	USPAT;	2003/09/21 16:17
50	8	alignment with source with sensor and attenuator		2003/03/21 10.17
	1		US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	

51	23	test with source with sensor and attenuator	USPAT;	2003/09/21 16:17
			US-PGPUB;	
			ЕРО; ЛРО;	
ļ			DERWENT;	
			IBM_TDB	
52	67	source with sensor and attenuator with controller	USPAT;	2003/09/21 16:17
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM_TDB	
53	0	(source with sensor and attenuator with controller) and 250/ccls./	USPAT;	2003/09/21 16:18
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM_TDB	
54	5	(source with sensor and attenuator with controller) and 250/\$.ccls.	USPAT;	2003/09/21 16:18
			US-PGPUB;	
			ЕРО; ЈРО;	
	1		DERWENT;	
			IBM_TDB	